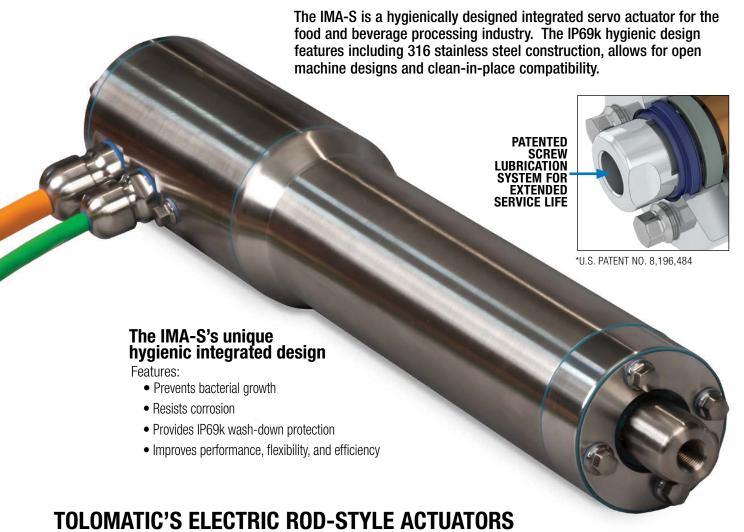


# IMA-S HYGIENIC INTEGRATED SERVO ACTUATOR



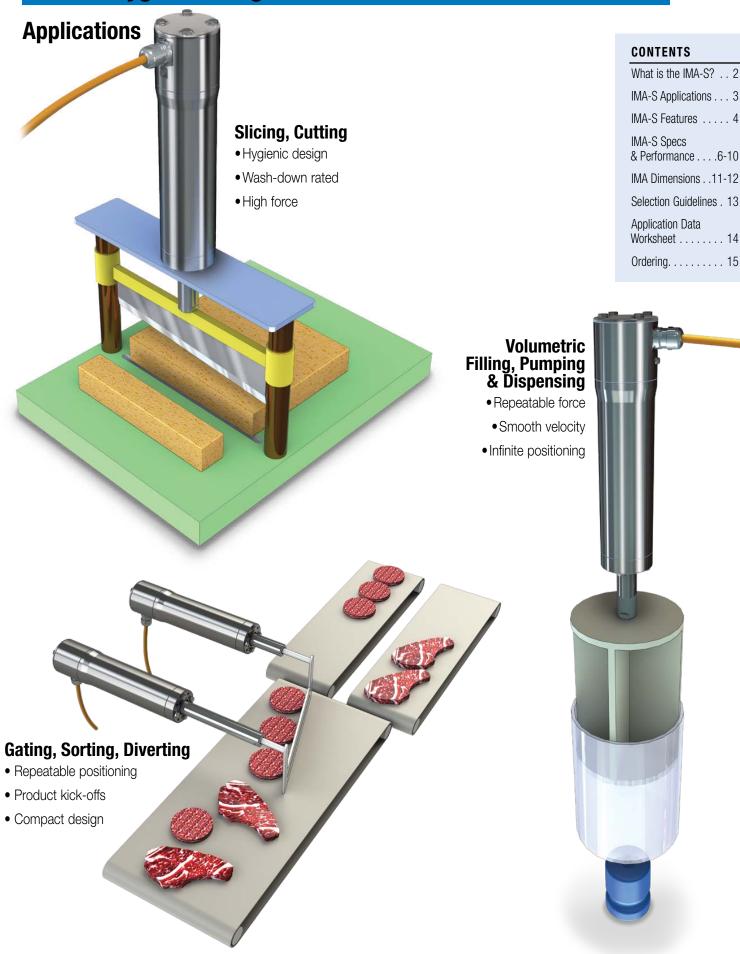
**LINEAR SOLUTIONS MADE EASY** 

## Designed for the most demanding food & beverage applications



	ERD	RSA	RSX	GSA	IMA
	Rod-Style Actuator	Rod-Style Actuator	Rod-Style Actuator	Guided Rod-Style Actuator	Integrated Servo Actuator
Force up to:	35 kN (7,868 lbf)	58 kN (13,039 lbf)	177.9 kN <i>(40,000 lbf)</i>	4.23 kN <i>(950 lbf)</i>	30.6 kN (6,875 lbf)
Speed up to:	1473 mm/sec (58 in/sec)	3,124 mm/sec (123 in/sec)	760 mm/sec (29.9 in/sec)	3,124 mm/sec (123 in/sec)	1,334 mm/sec (52.5 in/sec)
Stroke Length up to:	1000 mm (39.4 in)	1,524 mm (60 in)	1500 mm <i>(59 in)</i>	914 mm <i>(36 in)</i>	457 mm (18 in)
Screw/Nut Type	Solid, Ball & Roller	Solid, Ball & Roller	Roller	Solid & Ball	Ball & Roller
	Fo	r complete information	n see www.tolomatic.c	om or literature numb	per:
Literature Number:	2190-4000	3600-4166	2171-4001	3600-4166	2700-4000

(Not all models deliver maximum values listed, i.e.: Maximum thrust may not be available with maximum speed)



# **IMA-S: HYGIENIC INTEGRATED SERVO ACTUATOR**

# **○ENDURANCE TECHNOLOGY**

Endurance Technology features are designed for maximum durability to provide extended service life.

•Clean-in-place compatible

The IMA-S is a hygienically designed integrated servo actuator for the food and beverage processing industry. The hygienic design features all 316 stainless steel construction, IP69k ingress protection, blue seals/o-rings, and hygienic fasteners/cord grips allowing for open machine designs and clean-in-place compatibility. The product line also includes the IMA-SA model which incorporates an internal anti-rotate feature eliminating the need for an external guidance mechanism making it a perfect actuator for applications such as volumetric filling and pumping.



- cogging torque for smooth, repeatable motion
- Low electric time constant motor for quick response
- •Power dense
- 230 Vac or 460 Vac windings



 Compliant to FDA standards for human and food contact

Compatible with the following robot & drive/ controller manufacturers:

- Allen Bradley
  - Lenze
- Beckhoff Bosch Rexroth

Nidec

- Siemens
- And More

Kollmorgen

#### ● HIGH RESOLUTION FEEDBACK® **OPTIONS:**

- •Multi-turn absolute encoder, Hiperface, Hiperface DSL, EnDat 2.2
- Resolver
- •Incremental encoder

- •316 Stainless steel construction
- •Superior corrosion resistance

## BLUE GASKETS

- Chemically inert
- •Wear resistant
- FDA approved

 EHEDG (European Hygienic Engineering and Design Group) cord grip eliminates harborage points

#### MULTIPLE SCREW TECHNOLOGIES

- •Ball screws provide efficient motion at an economical price
- •Roller screws provide the highest force and longest life





## MA-SA INTERNAL

- Provides hygienic, internal anti-rotate feature, eliminating need for external quidance mechanism
- •Often used in volumetric filling and pumping applications

#### ADDITIONAL OPTIONS

- Brake
- •Externally threaded rod end
- Front flange mount
- Rear clevis mount
- Food grade grease
- Hygienic Fasteners
- FDA rod wipers

#### **Performance & Mechanical Specifications:**

SERIES	STACK	NUT/ SCREW	SCREW LEAD	DYNAMIC LOAD RATING (1 MIL REVS)	CONT. FORCE	PEAK FORCE	MAX. VELOCITY	BASE INERTIA <sup>2</sup>	NERTIA PER UNIT OF STROKE	BREAK- AWAY Torque	BACK DRIVE FORCE <sup>3</sup>
			mm	kN	kN	kN	mm/sec	kg-cm <sup>2</sup>	kg-cm <sup>2</sup> / mm	N-m	N
\ \	1	BN05	5	5.72	0.45	1.45	355	0.6550	0.00017	0.34	217.95
T2,	3	BN05	5	5.72	1.15	1.45	355	1.2572	0.00017	0.34	217.95
MA-ST22	1	BN10	10	4.40	0.22	1.36	497	0.6643	0.00021	0.34	111.20
$\leq$	3	BN10	10	4.40	1.15	1.45	497	1.2695	0.00021	0.34	111.20
	1	BN05	5	8.71	1.19	4.45	304	2.2924	0.00040	0.54	346.94
	3	BN05	5	8.71	3.46	4.45	292	4.4048	0.00040	0.54	346.94
	1	BN10	10	5.40	0.60	2.90	497	2.3138	0.00047	0.54	173.47
	3	BN10	10	5.40	1.73	4.00	497	4.4312	0.00047	0.54	173.47
E	1	BN20	10	11.39	0.30	1.45	497	2.5132	0.00156	0.54	88.96
IMA-ST33	3	BN20	10	11.39	0.87	3.44	497	4.7137	0.00156	0.54	88.96
₩	1	RN04	4	41.08	1.30	6.30	243	2.2937	0.00043	0.60	435.90
=	3	RN04	4	41.08	3.77	11.12	233	4.4079	0.00043	0.60	435.90
	1	RN05	5	45.42	1.04	5.04	304	2.2968	0.00044	0.60	346.94
	3	RN05	5	45.42	3.02	11.12	292	4.4116	0.00044	0.60	346.94
	1	RN10	10	45.42	0.52	2.52	497	2.3262	0.00054	0.60	173.47
	3	RN10	10	45.42	1.51	5.99	497	4.4488	0.00054	0.60	173.47
MA-SA33	3	RN04	4	45.42	3.77	11.12	233	4.8199	0.00118	0.72	524.86
1-S	3	RN05	5	45.42	3.02	11.12	292	4.8254	0.00119	0.72	418.11
≧	3	RN10	10	45.42	1.51	5.99	497	4.8991	0.00132	0.72	209.06
			in	lbf	lbf	lbf	in/sec	lb-in²	lb-in²/in	in-lb	lbf
2	1	BN05	0.197	1286	100	325	14.0	0.22383	0.00148	3	49
MA-ST22	3	BN05	0.197	1286	258	325	14.0	0.42960	0.00148	3	49
₩	1	BN10	0.394	989	50	305	19.6	0.22701	0.00182	3	25
_=	3	BN10	0.394	989	258	325	19.6	0.43381	0.00182	3	25
	1	BN05	0.197	1958	269	1000	12.0	0.78337	0.00351	4.8	78
	3	BN05	0.197	1958	779	1000	11.5	1.50519	0.00351	4.8	78
	1	BN10	0.394	1214	134	651	19.6	0.79067	0.00408	4.8	39
	3	BN10	0.394	1214	389	900	19.6	1.51421	0.00408	4.8	39
33	1	BN20	0.394	2560	67	326	19.6	0.85882	0.01355	4.8	20
-ST	3	BN20	0.394	2560	195	773	19.6	1.61076	0.01355	4.8	20
IMA-ST33	1_	RN04	0.157	9236	292	1417	9.6	0.78379	0.00372	5.3	98
=	3	RN04	0.157	9236	847	2500	9.2	1.50624	0.00372	5.3	98
	1	RN05	0.197	10211	234	1134	12.0	0.78485	0.00380	5.3	78
	3	RN05	0.197	10211	678	2500	11.5	1.50753	0.00380	5.3	78
	1	RN10	0.394	10211	117	567	19.6	0.79490	0.00468	5.3	39
	3	RN10	0.394	10211	339	1346	19.6	1.52022	0.00468	5.3	39
MA-SA33	3	RN04	0.157	10211	847	2500	9.2	1.64703	0.01022	6.4	118
A-S	3	RN05	0.197	10211	678	2500	11.5	1.64893	0.01029	6.4	94
$\subseteq$	3	RN10	0.394	10211	339	1346	19.6	1.67409	0.01149	6.4	47

<sup>&</sup>lt;sup>1</sup>1 Stack winding MV21 / 41 3 Stack winding MV23 / 43 <sup>2</sup>Value given is for a zero stroke

<sup>2</sup>Value given is for a zero stroke actuator † To be determined, visit www.tolomatic.com for up-to-date information

<sup>3</sup>In vertical applications an unpowered IMA-S will require a brake to maintain position if the load on the actuator exceeds this value



sizeit.tolomatic.com for fast, accurate actuator selection. GET THE EXACT ACTUATOR FOR YOUR APPLICATION REQUIREMENTS AND DUTY CYCLE.

#### **Performance & Mechanical Specifications:**

		IMA-ST22 (1 STACK, MV21/41)	IMA-ST22 (3 Stack, MV23/43)	IMA-ST33 (1 STACK, MV21/41)	IMA-ST33 (3 Stack, MV23/43)	IMA-SA33
EACE CIZE	mm	64	64	89	89	89
FACE SIZE	in	2.52	2.52	3.504	3.504	3.504
CTDOVE	mm	76.2 to 304.8	152.4 to 304.8	76.2 to 457.2	152.4 to 457.2	0 to 304.8
STROKE	in	3.0 to 12.0	6.0 to 12.0	3.0 to 18.0	6.0 to 18.0	0.0 to 12
*BASE WEIGHT	kg	4.8	6.1	10.2	12.5	13.9
DASE WEIGHT	lb	10.5	13.4	22.5	27.5	30.6
WEIGHT PER UNIT	kg/mm	0.0079	0.0079	0.0132	0.0132	0.0173
OF STROKE	lb/in	0.4408	0.4408	0.7390	0.7390	0.9690
SCREW LEAD BN		mm/300 = 0.051	in/ft = 0.002	(0.004 in/ft for IMA-	-S33BN20)	
ACCURACY RN		mm/300 = 0.010	in/ft = 0.0004			
SCREW LEAD BN		mm = 0.1	in = 0.004			
BACKLASH RN		mm = 0.051	in = 0.002			
TEMP RANGE	$^{\circ}\mathcal{C}$	-20 to 40				
TEIVII TIANGE	°F	-4 to 104				
IP RATING		IP69k (Static)				
REL. HUMIDITY (NON-CONDENSING)		5 to 90%				
SHOCK		20 gpeak, half sin	e, 6ms, 3 axis, IEC 6	0068-2-27		
VIBRATION		2.5 grms, 30-200	0 Hz, 3-axis, 1hr, IE0	C 60068-2-64		

<sup>\*</sup>Value given is for an actuator with minimum stroke, add weight per unit of stroke to calculate weight of entire actuator

#### **Motor Specifications:**

•			IMA <sup>.</sup>	-\$22		IMA-S33 IM			IMA-	SA33	
WINDING/MOTO	OR VOLTAGE	MV21	MV41	MV23	MV43	MV21	MV41	MV23	MV43	MV23	MV43
TORQUE	N-m/A Peak	0.37	0.75	0.49	0.93	0.61	1.21	0.62	1.21	0.62	1.21
CONSTANT (Kt)	in-lb/A Peak	3.3	6.6	4.3	8.2	5.4	10.7	5.5	10.7	5.5	10.7
VOLTAGE Constant (K <sub>e</sub> )	V/Krpm Peak	51	102	61	122	81	160	79.8	154	79.8	154
CONTINUOUS	N-m	0.42	0.42	1.07	1.07	1.12	1.12	3.24	3.24	3.24	3.24
STALL TORQUE	in-lb	3.7	3.7	9.5	9.5	9.9	9.9	28.7	28.7	28.7	28.7
CONTINUOUS STALL CURRENT	A <sub>RMS</sub>	0.8	0.4	1.55	0.775	1.3	0.65	3.7	1.85	3.7	1.85
PEAK TORQUE	N-m	2.54	2.54	4.51	4.51	5.42	5.42	13.22	12.88	13.22	12.88
PEAR TUNQUE	in-lb	22.5	22.5	39.9	39.9	48	48	117	114	117	114
PEAK CURRENT	A <sub>RMS</sub>	4.8	2.4	6.6	3.45	6.3	3.3	15	7.5	15	7.5
RESISTANCE	Ohms	18.1	72.4	7.1	28.3	10	40.1	2.07	8.3	2.07	8.3
INDUCTANCE	mH	10.7	42	4.5	18	13.6	54.1	3.8	15	3.8	15
BUS VOLTAGE	V <sub>RMS</sub>	230	460	230	460	230	460	230	460	230	460
SPEED @ RATED V RPM			4,264			3,650 3,500			500	3,5	500
NO. OF POLES						8	3				

RoHs Compliant Components;

c**™**us (€,

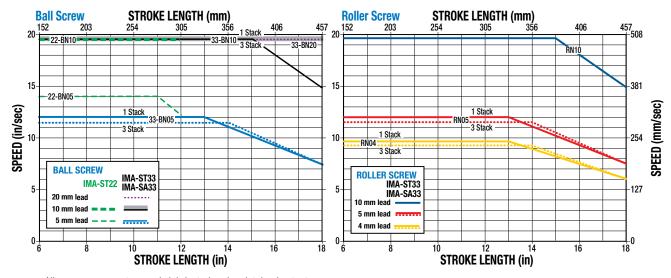
Performance data was validated using an aluminum face mount plate: IMA22/33 (8.25" x 7.0" x 0.7");

 $Ambient \ Temperature = 77^{\circ}F \ \textit{(25^{\circ}C)}; \ Elevation < 3281' \ \textit{(1,000 m)}; \ Drive \ specifications: Sinusoidal \ Commutation \ and \ PWM \ Voltage \ Source$ 

#### **CRITICAL SPEED**

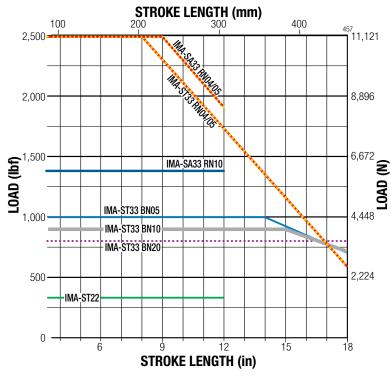
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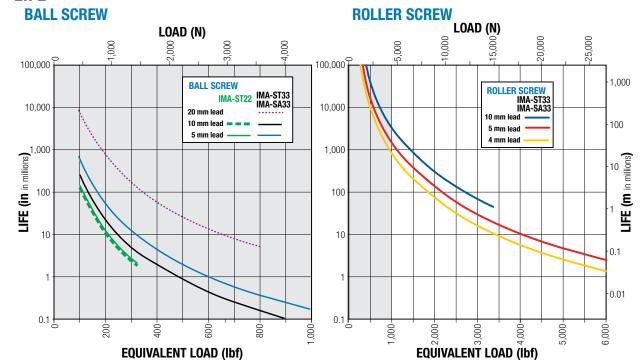
All curves represent properly lubricated and maintained actuators.

#### **ROLLER SCREW BUCKLING LOAD**



All curves represent properly lubricated and maintained actuators.

#### LIFE



NOTE: The L<sub>10</sub> expected life of a ball screw linear actuator is expressed as the linear travel distance that 90% of properly maintained ball screw manufactured are expected to meet or exceed. This is not a guarantee and this graph should be used for estimation purposes only.

The underlying formula that defines this value is:  $(\mathbf{C} - \mathbf{C})^3 \cdot \mathbf{C} = \mathbf{C}$ 

 $L_{10}$ Travel life in millions of units (in or mm), where:

**C** = Dynamic load rating (lbf) or (N)

**P**<sub>e</sub> = Equivalent load (lbf) or (N) If load is constant across all movements then:

Use the 'Equivalent Load' and calculation below, when the load is not constant throughout the entire stroke. In cases where there is only minor variation in loading, use greatest load for life calculations.

Where: 
$$\mathbf{P}_{e} = \sqrt[3]{\frac{L_{1}(\mathbf{P}_{1})^{3} + L_{2}(\mathbf{P}_{2})^{3} + L_{3}(\mathbf{P}_{3})^{3} + L_{n}(\mathbf{P}_{n})^{3}}{L}}$$

 $\mathbf{P}_{e}$  = Equivalent load (lbf) or (N)

 $\mathbf{P}_{n}$  = Each increment at different load (lbf) or (N)

**L** = Total distanced traveled per cycle (extend + retract stroke)  $[L = L_1 + L_2 + L_3 + L_n]$ 

IMAS 9

 $\mathbf{L}_{n}$ = Each increment of stroke at different load (in) or *(mm)* 

#### **RE-LUBRICATION RECOMMENDATION:**

**IMA-ST33, IMA-SA33:** Lubrication requirements for IMA-S electric actuators depend on the motion cycle (velocity, force, duty cycle), type of application, ambient temperature, environmental surrounding and various other factors.

For many general purpose applications, Tolomatic ball screw actuators are typically considered lubricated for life unless otherwise specified, such as those actuator models outfitted with a re-lubrication feature. For roller screw or ball screw actuators outfitted with a re-lubrication feature. Tolomatic recommends to re-lubricate the actuator at least once per year or every 1,000,000 cycles, whichever comes first, to maximize service life. For more demanding applications such as pressing, high frequency or other highly stressed applications, the re-lubrication interval for these actuators will vary and will need to be more frequent. In these

demanding applications, it is recommended to execute at least 5 full stroke moves every 5,000 cycles of operation (or more frequent if possible) to re-distribute the grease within the actuator.

Re-lubricate with

standard Tolomatic

Grease #2744-9099 or optional Food grade grease #2733-1303 into the grease zerk located on the rod end.

IMA-ST33	2.5 + [0.010 x L (mm)]	g
IMA-SA33	4.8 + [0.010 x L (mm)]	g
IMA-ST33	$0.09 + [0.009 \times L \text{ (in)}]$	OZ
IMA-SA33	0.17 + [0.009 x L (in)]	0Z

L=stroke length (mm or in)

NOTE: IMA22ST does not accommodate relubrication



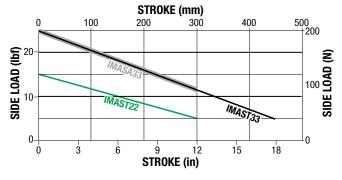
In some applications oil may leak from the grease zerk. In contamination sensitive applications replace grease zerk with plug.

#### SIDE LOAD CONSIDERATIONS

The IMA-S integrated motor actuator is not meant to be used in applications where side loading occurs. Loads must be guided and supported. Loads should be aligned with the line of motion of the thrust rod. Side loading will affect the life of the actuator.



#### IMA-S SIDE LOAD SPECIFICATIONS



#### **BRAKE CONSIDERATIONS**

An un-powered IMA-S will require a brake to maintain its position if the force on the actuator exceeds Back Drive Force listed in the table on page IMAS 6.

A brake can be used with the actuator to keep it from backdriving, typically in vertical applications. A brake may be used for safety reasons or for energy savings allowing the actuator to hold posi-

tion when un-powered. See page IMAS 15 for ordering information.



NOTE: The optional Spring-Applied / Electronically-Released Brake requires 24V power. Input current

IMA-ST22 - 0.35 Amps; IMA-S 33 - 0.43 Amps;

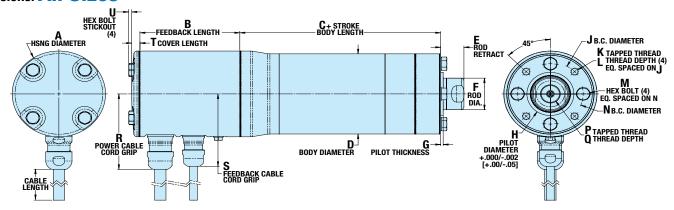
#### **Brake Specifications:**

ACTUATOR SIZING	www.tolomatic.com OR			
CALL TOLON	MATIC AT 1-800-328-2174.			
We will provide any assistance needed to determine the proper actuator for the job.				

	<b>SERIES</b>	IMA-ST22	IMA-ST33	IMA-SA33
ROTOR	gm-cm <sup>2</sup>	19	73	73
INERTIA	oz-in <sup>2</sup>	0.052	0.112	0.112
CURRENT	Amp	0.35	0.43	0.43
HOLDING	N-m	1.6	4.0	4.0
TORQUE	in-lb	14	35	35
ENGAGE TIME	mSec	75	40	40
DISENGAGE TIME	mSec	20	50	50
VOLTAGE	Vdc		24	

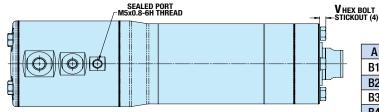
**Dimensions: All Sizes** 

## **DIMENSIONS**



	ST22	ST33	SA33
Α	76.2	95.3	95.3
B1	87.7	80.0	80.0
B2	119.1	121.4	121.4
В3	113.9	102.0	102.0
B4	142.7	140.1	140.1
C1**	123.7	158.8	381.6
C2**	126.2	161.4	384.1
D	64.0	89.0	89.0
E1	18.4	23.7	23.7
E2	15.9	21.2	21.2
F	25.38	35.00	35.00
G*	2.54	2.54	2.54
H *	35.500	48.000	48.000
J *	48.00	70.00	70.00
K *	М6х 1.0-6Н	М8х 1.25-6Н	<i>M8x</i> 1.25-6H
L*	12.5	13.0	13.0
M	M5	M8	M8
N	48.00	67.00	67.00
Р	M12x 1.25-6H	M20x 1.5-6H	<i>M20x</i> 1.5-6H
Q	16.0	25.4	25.4
R†	73.6	83.8	83.8
S†	70.4	80.4	80.4
T	8.1	8.4	8.4
U1	1.7	3.1	3.1
U2	5.5	9.1	9.1
V1	4.5	6.3	6.3
V2	8.3	12.0	12.0

Dimensions in millimeters



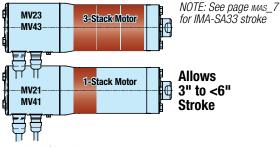
**ST33** 

#### **KEY FEATURES:** 1-STACK & 3-STACK MOTORS

#### **ST22** MV23/43 MV21/41 SERIES mm | 76.2 to 304.8 | 152.4 to 304.8 **STROKE** 3.0 to 12.0 6.0 to 12.0 in N up to 1,446 up to 1,446 PEAK FORCE lbf up to 325 up to 325

SE	RIES	MV21/41	MV23/43
STROKE	mm	76.2 to 457.2	152.4 to 457.
SINUKE	i.a	20+2100	C 0 to 10 0

6.0 to 18.0 in | 3.0 to 18.0 | up to 4,673 up to 7,562 Ν PEAK FORCE lbf up to 1,050 up to 1,700



- \* Not compatible with PCD option
- \*\* C1 for standard actuator; C2 for actuator with PCD option
- † Only 1 cord grip required with Sick Hiperface DSL (no "S", separate feedback cable); 22 size (74.9 mm [2.49"]); 33 size (85.4 mm [3.36"])

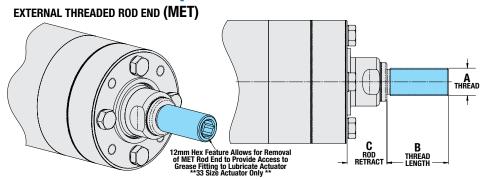
	Units	ST22	ST33	SA33		
Α	in	3.00	3.75	3.75		
B1	in	3.45	3.15	3.15		
B2	in	4.69	4.78	4.78		
В3	in	4.49	4.01	4.01		
B4	in	5.62	5.51	5.51		
C1**	in	4.87	6.25	15.02		
C2**	in	4.97	6.35	15.12		
D	in	2.52	3.50	3.50		
E1	in	0.72	0.93	0.93		
E2	in	0.62	0.83	0.83		
F	in	0.999	1.378	1.378		
G *	in	0.100	0.100	0.100		
H *	in	1.3976	1.8898	1.8898		
J *	in	1.890	2.756	2.756		
K*	mm	М6х 1.0-6Н	М8х 1.25-6Н	М8х 1.25-6Н		
L*	in	0.49	0.51	0.51		
М	mm	M5	M8	M8		
N	in	1.890	2.638	2.638		
Р	mm	M12x 1.25-6H	M20x 1.5-6H	<i>M20x</i> 1.5-6H		
Q	in	0.63	1.00	1.00		
R†	in	2.90	3.30	3.30		
S†	in	2.77	3.16	3.16		
Т	in	0.32	0.33	0.33		
U1	in	0.07	0.12	0.12		
U2	in	0.22	0.36	0.36		
V1	in	0.18	0.25	0.25		
V2	in	0.33	0.47	0.47		
Dimensions in inches (threads are metri						

Item	Code	Description			
	CA2 A2N	Allen Bradley VP Connector, SICK Hiperface DSL			
B1	CT2 A2N	Tolomatic Standard VP Connector, SICK Hiperface DSL			
	FA2 A2N	Allen Bradley Flying Lead, SICK Hiperface DSL			
	FT2 A2N	Tolomatic Standard Flying Lead, SICK Hiperface DSL			
	CA2 A2B	Allen Bradley VP Connector, SICK Hiperface DSL, Brake			
B2	CT2 A2B	Tolomatic Standard VP Connector, SICK Hiperface DSL, Brake			
DZ	FA2 A2B	Allen Bradley Flying Lead, SICK Hiperface DSL, Brake			
	FT2 A2B	Tolomatic Standard Flying Lead, SICK Hiperface DSL, Brake			
	FA1 A1N	Allen Bradley Flying Lead, SICK Hiperface			
	FT1 A1N	Tolomatic Standard Flying Lead, SICK Hiperface			
B3	FT1 D1N	Tolomatic Standard Flying Lead, Incremental			
	FT1 H1N	Tolomatic Standard Flying Lead, Heidenhein Endat 2.2			
	FT1 R1N	Tolomatic Standard Flying Lead, Resolver			

Item	Code	Description
	FA1 A1B	Allen Bradley Flying Lead, SICK HIPERFACE, Brake
	FT1 A1B	Tolomatic Standard Flying Lead, SICK HIPERFACE, Brake
B4	FT1 D1B	Tolomatic Standard Flying Lead, Incremental, Brake
	FT1 H1B	Tolomatic Standard Flying Lead, Heidenhein Endat 2.2, Brake
	FT1 R1B	Tolomatic Standard Flying Lead, Resolver, Brake
C1	_	Standard
C2	PCD	With PCD Option
E1	_	Standard
E2	PCD	With PCD Option
U1	_	Standard
U2	HYG2	With HYG2 Option
V1	_	Standard
V2	HYG2	With HYG2 Option



## Dimensions: Rod End Options



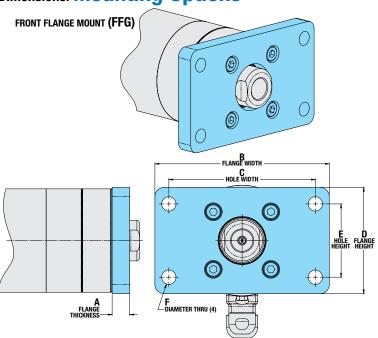
	ST22	ST33	SA33
Α	M16x 1.5-6g	M20x 1.5-6g	M20x 1.5-6g
В	37.3	44.5	44.5
С	18.4	28.8	28.8

Dimensions in millimeters

	UNITS	ST22	ST33	SA33
Α	mm M16x 1.5-6g		M20x 1.5-6g	M20x 1.5-6g
<b>B</b> in 1.47		1.75	1.75	
С	in	0.72	1.13	1.13

Dimensions in inches (threads are metric)

## **Dimensions: Mounting Options**



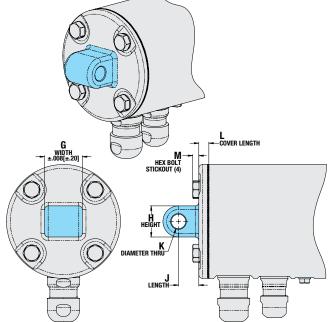
	ST22	ST33	SA33	
Α	11.2	15.0	15.0	
В	117.3	150.0	150.0	
С	100.0	126.0	126.0	
D	67.3	91.4	91.4	
Е	50.0	63.0	63.0	
F	8.7	12.3	12.3	

Dimensions in millimeters

	ST22	ST33	SA33
Α	0.44	0.59	0.59
В	4.62	5.91	5.91
С	3.94	4.96	4.96
D	2.65	3.60	3.60
Е	1.97	2.48	2.48
F	0.34	0.48	0.48

Dimensions in inches

REAR CLEVIS MOUNT (PCD)



	ST22	ST33	SA33		
G	25.6	31.6	31.6		
Н	22.0	26.0	26.0		
J	14.1	17.1	17.1		
K	10.036/ 10.000	12.043/ 12.000	12.043/ 12.000		
L	8.1	8.4	8.4		
M1*	3.6	5.2	5.2		
M2*	7.4	10.9	10.9		

Dimensions in millimeters

	ST22	ST33	SA33
G	1.01	1.24	1.24
Н	0.87	1.02	1.02
J	0.56	0.67	0.67
K	0.3951/ 0.3937	0.4741/ 0.4724	0.4741/ 0.4724
L	0.32	0.33	0.33
M1*	0.14	0.20	0.20
M2*	0.29	0.43	0.43

Dimensions in inches

<sup>\*</sup>M1 Standard actuator; M2 with HYG2 option

#### **Selection Guidelines**

#### ESTABLISH MOTION PROFILE

Using the application stroke length, desired cycle time and loads establish the motion profile details.

# COMPARE OPERATING (PEAK) FORCE AND VELOCITY TO OPERATING REGION

Calculate the application required operating (peak) force and velocity and compare to tables on pages IMAS\_6. The calculated force and velocity must fall within the operating region of the actuator.

## COMPARE SEVERE DUTY (CONTINUOUS) FORCE AND VELOCITY TO SEVERE DUTY REGION

Calculate the RMS force and velocity required and compare to tables on pages IMAS\_6-7. The calculated force and velocity must fall within the severe duty region.

$$\mathbf{T}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{T}_{i}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}} \quad \mathbf{V}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{V}_{i}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}}$$

## CONSIDER SCREW/NUT CHOICES

Choose roller nuts for its longer life (see Life graph on page IMAS\_9) and higher peak loads (see graphs on pages IMAS\_8). Ball nuts are cost competitive and more efficient (see table on page IMAS\_6).

SCREW ACCURACY			
Roller Nut	± 0.0004"/ft.	± 0.0102mm/300mm	
Ball Nut	± 0.002"/ft.	± 0.051mm/300mm	

### VERIFY CRITICAL SPEED OF THE SCREW

Verify that the application's peak linear velocity does not exceed the critical speed value for the size and lead of the screw selected.

## VERIFY AXIAL BUCKLING STRENGTH OF THE SCREW

Verify that the peak force does not exceed the critical buckling force for the size of the screw selected.

## MOTOR WINDINGS & VOLTAGES

Choose motor windings optimized for 230 Vac and 460 Vac voltage busses. The 1 stack motor (MV21-230V & MV41-460V), available for the IMA-S22/33, allows strokes of 3" (76.2mm) vs the minimum 6" (152.4mm) stroke required for 3 stack motors, providing the force needed for many applications in a more compact, lighter weight package

### CALCULATE LUBRICATION INTERVAL

See page IMAS\_10 for an overview and IMA-S Users Guide (#2700-4016) for complete instructions to calculate lubrication interval.

### **TEMPERATURE**

The IMA-S is intended to operate in an environment with an ambient temperature between -4 to +104°F, (-10 to +40°C). Performance should be de-rated if the ambient temperature is above 77°F (25°C). Contact the factory if the ambient temperature does not fit within this range. NOTE: Temperature

of the actuator's body can approach 180°F (82°C) in aggressive applications. Adequate clearance to ensure actuator's ambient conditions do not rise drastically should be allowed.

BRAKE CONSIDERATIONS

An un-powered IMA-S will require a brake to maintain its position if the force on the actuator exceeds Back Drive Force listed in the table on page IMAS 8.

A brake can be used with the actuator to keep it from back-driving, typically in vertical applications. A brake may be used for safety reasons or for energy savings allowing the actuator to hold position when un-powered. See page <code>IMAS\_15</code> for ordering information.

NOTE: The optional Spring-Applied / Electronically Released Brake requires 24V power. Input current rating: IMA22 - 0.35 Amps; IMA33 - 0.43 Amps;

## CHOOSE MOTOR CONNECTORS & FEEDBACK DEVICE

Connector choice and wiring emulates popular motor manufacturers for compatibility.

Cable/connector options include:

- Allen Bradley VP series
- Tolomatic standard
- Flying leads
- Cables are available in 3m, 5m and 10m lengths

Feedback options include:

- Incremental Encoder
- Absolute Encoder, Hiperface, Hiperface DSL, EnDat 2.2

ACTUATOR

**SIZING** 

Resolver

Contact Tolomatic for additional motor connectors, feedback combinations and motor files for third party drives.

## 1 2 CONSIDER MOUNTING & ROD END OPTIONS

Examine mounting options dimensional drawings on page IMAS\_12. Standard mounting on the IMA-S are 4 tapped holes on the front rod end face of the actuator. Other fixed mounting option is the Front Flange Mount (FFG). Pivoting mount option is the Rear Clevis Mount (PCD).

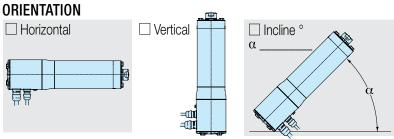
Rod End Option is: External Threaded Rod End (MET).

NOTE: Regardless of the mounting option chosen, care must be taken to ensure that the load is guided and in-line with the force rod's line of motion. Misalignment of the force rod's line of motion will cause degradation in the actuator's expected life.

# CONSIDER ENVIRONMENTAL RATING AND ANTI-ROTATE OPTIONS

The environmental rating for a standard IMA-S is IP69K for protection against water and dust ingress. Choose the Anti-Rotate Option (IMA-SA) if required. Call Tolomatic at 1-800-328-2174 for help in determining the best actuator for your application.

## **APPLICATION DATA WORKSHEET** Fill in known data. Not all information is required for all applications





☐ Load supported by actuator OR ☐ Load supported by other mechanism

MOVE PROFILE	STROKE LENGTH		PRECISION	
EXTEND  Move Distance	~	] millimeters (SM) etric)	Repeatability ☐ inch ☐ mil	limeters
inch ☐ millimeters  Move Timesec	NOTE: If load or force	e changes during cycle bers for calculations	<b>OPERATING ENVIRON</b> Temperature, Contamina	
Max. Speed mm/sec	EXTEND	RETRACT	·	
Dwell Time After Movesec  RETRACT	LOAD kg (U.S. Standard) (Metric)	LOAD   kg (U.S. Standard) (Metric)		
Move Distance millimeters  Move Time sec  Max. Speed mm/sec	FORCE   Ibf   N (U.S. Standard) (Metric)	FORCE   Ibf		
Dwell Time After Movesec	MOTION PROFILE  +   Speed ( )			Graph your most
NO. OF CYCLES per minute per hour  HOLD POSITION? Required Not Required During Power Loss  CONTACT			Time or Distance (	demanding cycle, including accel/decel, velocity and dwell times. You may also want to indicate load variations and I/O changes during the cycle. Label axes with proper scale and units.
CONTACT INFORMATION Name, Phone, Email Co. Name, Etc.				



USE THE TOLOMATIC SIZING AND SELECTION SOFTWARE AVAILABLE ON-LINE AT www.tolomatic.com OR... CALL TOLOMATIC AT 1-800-328-2174. We will provide any assistance needed to determine the proper actuator for the job.

FAX 1-763-478-8080

EMAIL help@tolomatic.com

## **Ordering**

MODEL SELECTION (MUST BE IN THIS ORDER)

OPTIONS (IN ANY ORDER)

## IMAST 33 RN05 SM304-8 MV23 CT2A2 N FFG HYG2 HYG3 CR5

#### MODEL

IMA-ST Stainless IMA StandardIMA-SA Stainless IMA Anti-Rotate

#### SIZE

22 Series Actuator (Anti-Rotate not available)33 Series Actuator

#### NUT/SCREW

crew/Nut combinations available

Screw/Nul combinations available				
22	33	33SA	Description	
BN05	BN05	_	Ball Nut, 5 mm lead	
BN10	BN10	_	Ball Nut, 10 mm lead	
_	BN20	_	Ball Nut, 20 mm lead	
_	RN04	RN04	Roller Nut, 4 mm lead	
_	RN05	RN05	Roller Nut, 5 mm lead	
_	RN10	RN10	Roller Nut, 10 mm lead	

#### STROKE LENGTH

**SM** \_ \_ .\_ Stroke, enter stroke length in millimeters

NOTE: See page IMAS\_7 for stroke min. & max.

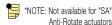
#### **MOTOR VOLTAGE**

MV21\* 230 Vac, Motor Voltage, 1 Stack Winding

**MV41\*** 460 Vac, Motor Voltage, 1 Stack Winding

**MV23** 230 Vac, Motor Voltage, 3 Stack Winding

**MV43** 460 Vac, Motor Voltage, 3 Stack Winding



#### **BRAKE OPTION**

N NO Brake B Brake

#### **ROD END OPTIONS**

Standard, female, internally threaded rod end

Male Externally Threaded

#### **MOUNTING OPTIONS**

Rod End

Standard Face Mount
 FFG Front Flange Mount
 PCD Clevis Mount, Rear
 Clevis Mount, Rear

(Rotated 90°)

#### OTHER OPTIONS\*

**LUB** Food Grade Grease

**HYG2** Hygienic Fasteners

**HYG3** FDA Rod Wipers

\*Order none, 1,2 or all 3

#### CABLES

CR3 Tolomatic standard
3m flying lead cables,
power and feedback

Tolomatic standard
CR5 5m flying lead cables,
power and feedback
Tolomatic standard

CR10 10m flying lead cables, power and feedback For custom cable lengths please con-

For custom cable lengths please con tact Tolomatic. Lead times will vary.



Contact Tolomatic for Lead Time

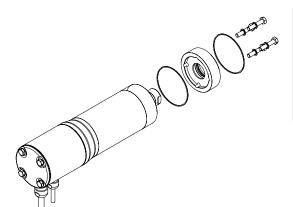
Some feedback devices are not compatible with some connectors. Contact Tolomatic for complete motor connector & feedback combination information

## MOTOR SERIES CONNECTORS | FEEDBACK DEVICE

Cable + Allen Bradley VP Connector	CA2	<b>A2</b>	SICK Hiperface DSL
Allen Bradley Flying Lead	FA1	<b>A1</b>	SICK Hiperface
Allen Bradley Flying Lead	FA2	<b>A2</b>	SICK Hiperface DSL
Cable + Tolomatic Std. VP Connector	CT2	A2	SICK Hiperface DSL
Tolomatic Std. Flying Lead	FT1	D1	Incremental

### MOTOR SERIES CONNECTORS FEEDBACK DEVICE

Tolomatic Std. Flying Lead	FT1 A1	SICK Hiperface
Tolomatic Std. Flying Lead	FT1 H1	Heidenhein Endat 2.2
Tolomatic Std. Flying Lead	FT1 R1	Resolver
Tolomatic Std. Flying Lead	FT2 A2	SICK Hiperface DSL



REPLACEABLE SEAL CARTRIDGE			
Description	IMA-ST22	IMA-ST33	IMA-SA33
Standard	2622-9070	2633-9070	2633-9070
Standard with Rear Clevis Mount (PCD_)	2622-9071	2633-9071	2633-9071
FDA Rod Wipers (HYG3)	2622-9072	2633-9072	2633-9072
FDA Rod Wipers (HYG3) with Rear Clevis Mount (PCD.)	2622-9073	2633-9073	2633-9073

## **The Tolomatic Difference** Expect More From the Industry Leader:



Unique linear actuator solutions with Endurance Technology<sup>SM</sup> to solve your challenging application requirements.



The fastest delivery of catalog products... Built-to-order with configurable stroke lengths and flexible mounting options.



Online sizing that is easy to use, accurate and always up-to-date. Find a Tolomatic electric actuator to meet your requirements.



Match your motor with compatible mounting plates that ship with any Tolomatic electric actuator.



Easy to access CAD files available in the most popular formats to place directly into your assembly.



Extensive motion control knowledge: Expect prompt, courteous replies to any application and product questions from Tolomatic's industry experts.

## **Also Consider These Other Tolomatic Products:**

#### **Electric Products**

Rod & Guided Rod Style Actuators, High Force Actuators, Screw & Belt Drive Rodless Actuators, Motors, **Drives and Controllers** 

"Foldout" Brochure #9900-9074





#### **Pneumatic Products**

Rodless Cylinders: Band Cylinders, Cable Cylinders, Magnetically Coupled Cylinders/Slides; Guided Rod Cylinder Slides

"Foldout" Brochure #9900-9075



#### **Power Transmission Products**

Gearboxes: Float-A-Shaft®, Slide-Rite®; Disc Cone Clutch; Caliper Disc Brakes

"Foldout" Brochure #9900-9076

## **OToloma EXCELLENCE IN MOTION**®

3800 County Road 116 Hamel, MN 55340, USA Phone: (763) 478-8000 Fax: (763) 478-8080 Toll-Free: 1-800-328-2174 sales@tolomatic.com

www.tolomatic.com

#### CHINA

**Tolomatic Automation Products** (Suzhou) Co. Ltd.

(ServoWeld® inquiries only)

No. 60 Chuangye Street, Building 2 Huqiu District, SND Suzhou Jiangsu 215011 - P.R. China

Phone: +86 (512) 6750-8506 Fax: +86 (512) 6750-8507

ServoWeldChina@tolomatic.com

**CERTIFIED BY DNV GL** = ISO 9001 = Certified site: Hamel, MN **EUROPE** 

**COMPANY WITH** 

**QUALITY SYSTEM** 

#### **Tolomatic Europe GmbH**

Elisabethenstr. 20 65428 Rüsselsheim Germany

Phone: +49 6142 17604-0 help@tolomatic.eu

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